

Stability and the effective metric

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Effective metric for a nonlinear scalar theory

$$S[\phi] = \int \sqrt{-g} \mathcal{L}(W) d^4x,$$

$$W = g^{\mu\nu} \nabla_\mu \phi \nabla_\nu \phi$$

Background metric

EOM:

$$\mathcal{L}_W \square \phi + \partial^\mu \phi (\partial_\mu W) \mathcal{L}_{WW} = 0$$

$$\phi = \phi_0 + \varepsilon \phi_1$$



$$(\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}) \phi_{1,\mu})_{,\nu} = 0.$$

+ eikonal approx.

$$\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}) = \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu}, \quad \text{“Effective metric”}$$

(all quantities evaluated at the background solution)

Goulart and SEP, 2011

IST 2015

$$(\sqrt{-g}(\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}) \phi_{1,\mu})_{,\nu} = 0.$$

$$\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}) = \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu},$$

$$(\sqrt{-\tilde{g}} \tilde{g}^{\mu\nu} \phi_{1,\mu})_{,\nu} = 0.$$

In the linear case,

$$\mathcal{L}(W, \phi) = W$$

the effective metric reduces to the background metric.

In the case of theories with more degrees of freedom there can be birefringence and/or bimetricity.

Goulart and SEP, 2009

From

$$(\sqrt{-\tilde{g}} \tilde{g}^{\mu\nu} \phi_{1,\mu})_{,\nu} = 0.$$

the action for the (high-energy) perturbations is

$$S_2 = \int \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu} \phi_{1,\mu} \phi_{1,\nu} d^3x.$$

$$\tilde{T}_{\mu\nu} = \frac{\delta S_2}{\delta \tilde{g}^{\mu\nu}}.$$



$$\tilde{T}^{\mu}_{\nu} = \tilde{g}^{\mu\lambda} \phi_{1,\lambda} \phi_{1,\nu} - \frac{1}{2} \delta^{\mu}_{\nu} \tilde{g}^{\alpha\beta} \phi_{1,\alpha} \phi_{1,\beta}$$

$$\tilde{\nabla}_{\mu} \tilde{T}^{\mu\nu} = 0.$$

Linear stability using the effective metric

(Moncrief, 1980, for a test perfect fluid in potential flux accreting onto a Schwarzschild black hole)

X^μ is a Killing vector of the background metric (hence of the eff. metric)



$$\tilde{\nabla}_\mu (X^\nu \tilde{T}_\nu^\mu) = 0,$$

$$\partial_\nu (\sqrt{-\tilde{g}} \tilde{X}^\mu \tilde{T}_\mu^\nu) = 0$$

Integrating in a 3-volume V

$$\tilde{X}^\nu = \delta_t^\nu$$

$$\int_V \partial_\nu (\sqrt{-\tilde{g}} \tilde{T}_t^\nu) d^3x = 0.$$

$$\int_V \partial_t (\sqrt{-\tilde{g}} \tilde{T}_t^t) d^3x + \int_V \partial_i (\sqrt{-\tilde{g}} \tilde{T}_t^i) d^3x = 0.$$

$$\int_V \partial_t(\sqrt{-\tilde{g}}\tilde{T}_t^t)d^3x + \int_V \partial_i(\sqrt{-\tilde{g}}\tilde{T}_t^i)d^3x = 0.$$

$$\tilde{E} = \int_V \sqrt{-\tilde{g}} \tilde{T}_t^t d^3x.$$

$$\frac{d\tilde{E}}{dt} = - \int_S dS_i \sqrt{-\tilde{g}} \tilde{T}_t^i.$$

Linear stability

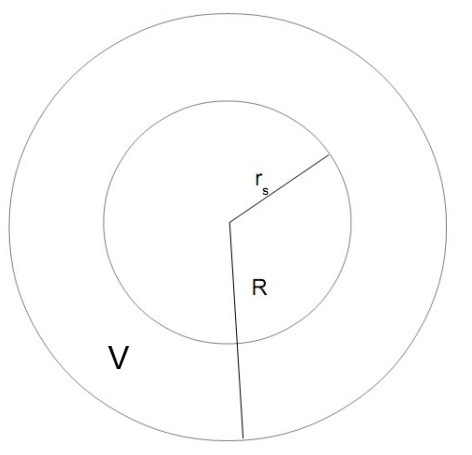


$$\frac{d\tilde{E}}{dt} \leq 0$$

and

$$\tilde{E} > 0$$

$$\tilde{T}_\nu^\mu = \tilde{g}^{\mu\lambda} \phi_{1,\lambda} \phi_{1,\nu} - \frac{1}{2} \delta_\nu^\mu \tilde{g}^{\alpha\beta} \phi_{1,\alpha} \phi_{1,\beta}$$



$$\tilde{T}_\nu^\mu = \tilde{g}^{\mu\lambda} \phi_{1,\lambda} \phi_{1,\nu} - \frac{1}{2} \delta_\nu^\mu \tilde{g}^{\alpha\beta} \phi_{1,\alpha} \phi_{1,\beta}$$

$$\frac{d\tilde{E}}{dt} = I_1 + I_2,$$

$$I_1 = - \oint_{S_R} \sqrt{-\tilde{g}} (\phi_{1,r} \phi_{1,t} \tilde{g}^{rr} + (\phi_{1,t})^2 \tilde{g}^{rt}) \Big|_R dS_r,$$

$$I_2 = \oint_{r_s} \sqrt{-\tilde{g}} (\phi_{1,r} \phi_{1,t} \tilde{g}^{rr} + (\phi_{1,t})^2 \tilde{g}^{rt}) \Big|_{r_s} dS_r,$$

r_s : “sonic horizon”

$$\tilde{E} = \int_V \sqrt{-\tilde{g}} \tilde{T}_t^t d^3x.$$

$$\tilde{T}_\nu^\mu = \tilde{g}^{\mu\lambda} \phi_{1,\lambda} \phi_{1,\nu} - \frac{1}{2} \delta_\nu^\mu \tilde{g}^{\alpha\beta} \phi_{1,\alpha} \phi_{1,\beta}$$

H1)

$$\sqrt{-\tilde{g}} \tilde{g}^{rr} \xrightarrow{r \rightarrow \infty} \sqrt{-g} g^{rr} = r^2 \sin \theta,$$

$$\tilde{g}^{rt} \xrightarrow{r \rightarrow \infty} 0$$

H2) The perturbations have finite energy:

$$\phi_{1,t} \sim \frac{a}{r^{\frac{3}{2} + \epsilon}};$$

$$\phi_{1,r} \sim \frac{a'}{r^{\frac{5}{2} + \epsilon}},$$

$$\epsilon > 0$$

$$r \rightarrow \infty$$

$$I_1 = - \oint_{S_R} \sqrt{-\tilde{g}} (\phi_{1,r} \phi_{1,t} \tilde{g}^{rr} + (\phi_{1,t})^2 \tilde{g}^{rt}) \Big|_{R \rightarrow \infty} dS_r,$$



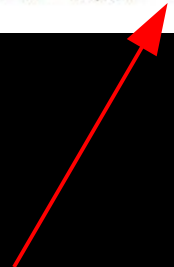
$$I_1 = 0$$

$$\frac{d\tilde{E}}{dt} = I_2 = \oint_{S_{r_s}} \sqrt{-\tilde{g}} (\phi_{1,r} \phi_{1,t} \tilde{g}^{rr} + (\phi_{1,t})^2 \tilde{g}^{rt}) \Big|_{r_s} dS_r,$$

$$\tilde{g}^{rr}(r_s) = 0$$



$$\frac{d\tilde{E}}{dt} = \int \sqrt{-\tilde{g}} (\phi_{1,t})^2 \tilde{g}^{rt} \Big|_{r_s} dS_r.$$



Linear stability



$$\frac{d\tilde{E}}{dt} \leq 0$$

$$\tilde{E} > 0$$

Example: Frolov (2004)

$$\mathcal{L}(W) = \frac{1}{2}(W - A)^2.$$

“Effective cosmological constant”
(Arkani-Hamed et al, 2003)

$$ds^2 = f dt^2 - f^{-1} dr^2 - r^2 d\Omega^2,$$

$$f(r) = 1 - r_g/r$$

Stationary solution + spherical symmetry



$$\phi = t + \psi(r),$$

EOM

$$\mathcal{L}_W \partial_r^* \psi = \alpha \frac{r_g^2}{r^2},$$

$$\partial_r^* \equiv f(r) \partial_r.$$

$$W = \frac{1 - (\partial_r^* \psi)^2}{f(r)},$$

$$\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}) = \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu},$$

$$M^{\mu\nu} = \mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} g^{\mu\alpha} \phi_{0,\alpha} g^{\nu\beta} \phi_{0,\beta}$$

$$\sqrt{-\tilde{g}} = (-g)\sqrt{M}$$

$$\tilde{g}^{\mu\nu} = \frac{M^{\mu\nu}}{\sqrt{-g}\sqrt{M}}$$

$$\mathcal{L}(W) = \frac{1}{2}(W - A)^2.$$

$$W = \frac{1 - (\partial_r^* \psi)^2}{f}$$

→ **1** for $r \rightarrow \infty$

$$\sqrt{-\tilde{g}} \tilde{g}^{rr} \rightarrow \sqrt{-g} g^{rr} = r^2 \sin \theta,$$

$r \rightarrow \infty$

$$\tilde{g}^{rr} \rightarrow 0$$

$r \rightarrow \infty$

Back to stability:

$$\frac{d\tilde{E}}{dt} = \int \sqrt{-\tilde{g}} (\phi_{1,t})^2 \tilde{g}^{rt} \Big|_{r_s} dS_r.$$

$$\mathcal{L}(W) = \frac{1}{2} (W - A)^2.$$

$$\phi = t + \psi(r),$$

$$\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} \phi_0'^{\mu} \phi_0'^{\nu}) = \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu},$$



$$\sqrt{-\tilde{g}} \tilde{g}^{tr} = \sqrt{-g} 2(-1)\psi_{,r}$$

$$\frac{d\tilde{E}}{dt} = -2 \int r^2 \sin\theta \psi_{,r} \phi_{1,t}^2 d\theta d\varphi \Big|_{r_s}$$

(only the sign of $\psi_{,r}$ is needed)

There is only one solution that goes from infinity (with null radial velocity) to r_g , and satisfies the condition $\psi_{,r} > 0$ (Frolov 2004)

→ The rhs is negative

We still need to prove that $\tilde{E} > 0$

$$\tilde{T}_t^t = \frac{1}{2}\tilde{g}^{tt}(\partial_t\phi_1)^2 - \frac{1}{2}\tilde{g}^{ij}(\partial_i\phi_1)(\partial_j\phi_1),$$

$$\tilde{g}^{ij} = \text{diag}(\tilde{g}^{rr}, \tilde{g}^{\theta\theta}, \tilde{g}^{\varphi\varphi}),$$

$$\tilde{g}^{\mu\nu} = \frac{M^{\mu\nu}}{\sqrt{-g}\sqrt{M}},$$

$$M^{\mu\nu} \equiv \mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW}\Phi^{\mu\nu}|_0.$$

$$\Phi^{\mu\nu} \equiv g^{\mu\alpha}\phi_{,\alpha}g^{\nu\beta}\phi_{,\beta}.$$

$$\mathcal{L}_W > 0$$

$$\mathcal{L}_{WW} = 1$$

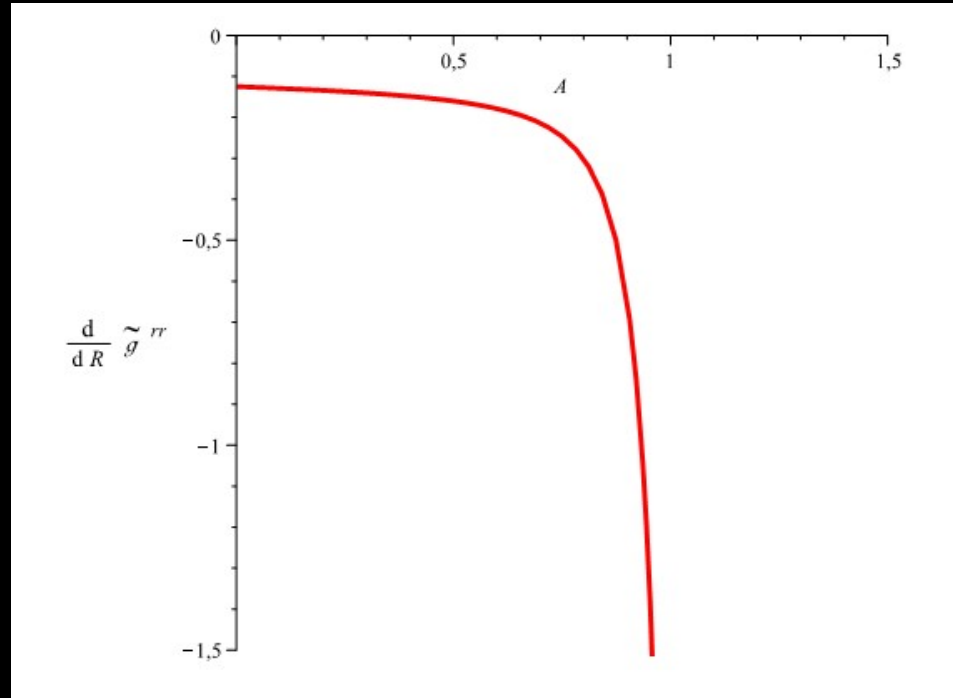
→ The tt , $\theta\theta$, and $\phi\phi$ components have the right sign.

To prove that the rr component is negative outside the horizon:

1) It only has one zero (at the sonic horizon)

$$M^{rr} = 3v^2 + Af - 1 \quad \text{OK!}$$

2) Its derivative is negative at the sonic horizon:



→ The system is linearly stable under high-energy perturbations.

(C. A. Paz Rivasplata, J. M. Salim, SEPB, PRD 2014)

Stability using the effective potential

$$(\sqrt{-\tilde{g}} \tilde{g}^{\mu\nu} \phi_{1,\mu}),_{\nu} = 0.$$

$$\begin{aligned} dt &= dT - \frac{\tilde{g}_{rt}}{\tilde{g}_{tt}} dR, \\ dr &= dR. \end{aligned}$$

$$\sqrt{-g} (\mathcal{L}_W g^{\mu\nu} + 2\mathcal{L}_{WW} \phi_0'^{\mu} \phi_0'^{\nu}) = \sqrt{-\tilde{g}} \tilde{g}^{\mu\nu},$$

$$\tilde{G}^{tt} = \frac{\tilde{g}^{tt} \tilde{g}^{rr} - \tilde{g}^{rt}}{\tilde{g}^{rr}},$$

$$\tilde{G}^{rr} = \tilde{g}^{rr},$$

$$\tilde{G}^{\theta\theta} = \tilde{g}^{\theta\theta},$$

$$\tilde{G}^{\varphi\varphi} = \tilde{g}^{\varphi\varphi}.$$

$$\tilde{G}^{rr}(r_s) = 0,$$

$$\partial_{\mu}(\sqrt{\tilde{G}} \tilde{G}^{\mu\nu} \partial_{\nu} \phi_1) = 0.$$

Tortoise coordinate

$$d\rho^* = F \mathcal{L}_W dr,$$

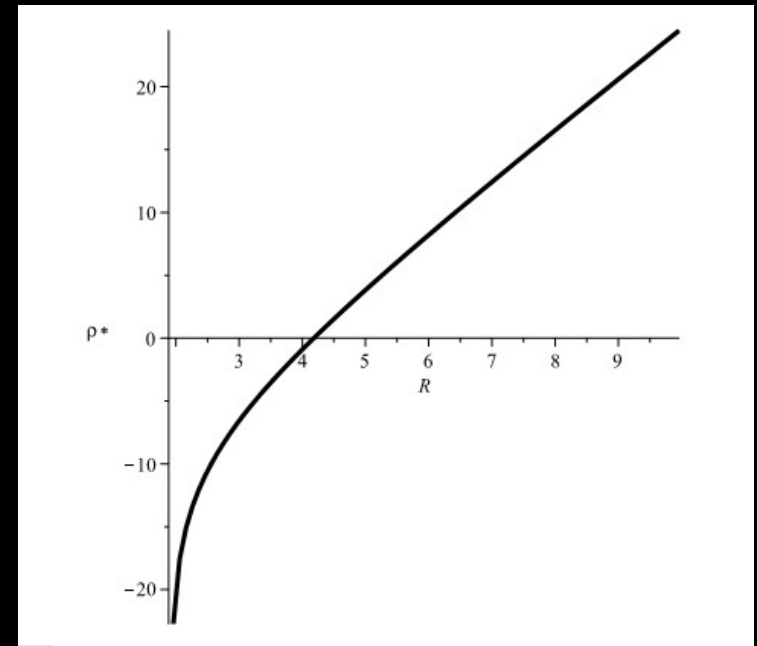
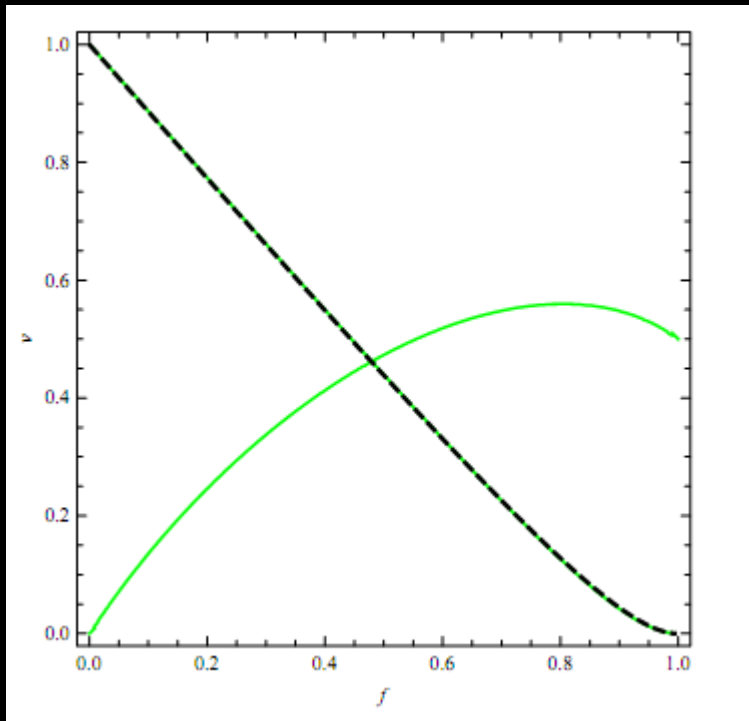
$$F = -\tilde{G}^{rr}$$

$\rho^* = \rho^*(r)$ is calculated numerically, using the parametrization

$$v = \frac{(f-1)^2}{1-a_1 f} - a_2 f,$$

$$a_1 = 0.8599,$$

$$a_2 = 0.0003.$$



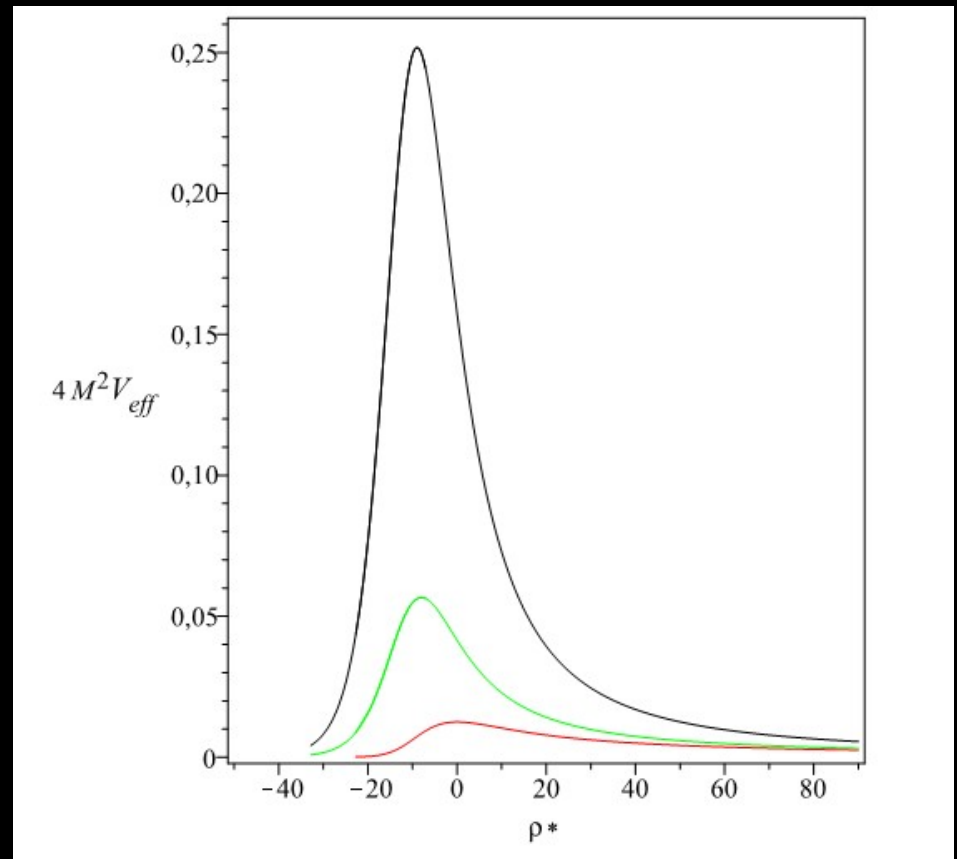
$$\partial_\mu (\sqrt{\tilde{G}} \tilde{G}^{\mu\nu} \partial_\nu \phi_1) = 0.$$

$$\phi_1 = \exp(-i\omega t) \beta(r) Y_{lm}(\theta, \varphi).$$

After a rather long and straightforward calculation,

$$\frac{d^2 \beta}{d\rho_*^2} + (\omega^2 - V_{eff}(r)) \beta = 0$$

The explicit form of the function $\psi(r)$ was needed.



(C. A. Paz Rivasplata, J. M. Salim, SEPB, PRD 2014)

Positivity of the potential is a sufficient condition for linear stability (Wald, 1979).

Conclusions

- * The propagation of perturbations of a nonlinear theory is governed by the effective metric, which depends of the nonlinearity of the theory and of the background solution.
- * In the case of a test scalar field in stationary accretion on a Schwarzschild bh, the sign of the time derivative of the energy of the perturbations can be determined through a surface integral, that depends only of the sign of the radial derivative of the background solution at r_s .
- * Using this integral plus the positivity of the energy of the perturbations, we showed that the model by Frolov is stable under high-energy perts.
- * The result coincides with the numerical analysis of the nonlinear stability of particular solutions (Akhoury et al 2011).

- * The integral method requires less calculations than the traditional method of the effective potential.
- * The method yields a necessary and sufficient condition, while $V_{eff} > 0$ is a sufficient condition.
- * Only the sign of the radial derivative of the solution at r_s is needed.
- * Near-horizon behaviour of the fields? Generalization to angular momentum? Work in progress with Azucena Paz Rivasplata and Rodrigo Maier).